

## Transformations in 3-D

### Starter

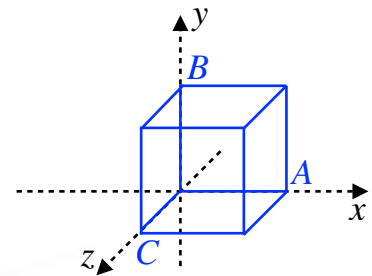
1. The matrix  $\mathbf{M} = \begin{pmatrix} 2 & -1 \\ 2 & 4 \end{pmatrix}$  represents a transformation.

- (a) Find all the invariant points of  $\mathbf{M}$ .  
 (b) Show that  $\mathbf{M}$  has no invariant lines through the origin.

2. Prove that the line  $y = 2x - 1$  is mapped onto itself under the transformation  $\begin{pmatrix} 3 & -1 \\ 4 & -1 \end{pmatrix}$ .

3. By considering the unit cube, find the matrix which causes a reflection in the  $y - z$  plane.

**Hint:** The  $y - z$  plane is also called the  $x = 0$  plane.



### Notes

Rotations and reflections in 2-D and 3-D are different in the following ways:

	Shapes rotate about a...	Shapes are reflected in a...	Consider the...
2-D	...point	...line	...unit square
3-D	...line	...plane	...unit cube

### Reflections

**E.g. 1** From the starter, the matrix which causes a reflection in the  $y - z$  plane (or  $x = 0$  plane) is

$\begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$ . Hence state the matrix that causes a reflection in:

- (a)  $x - z$  plane or  $y = 0$  plane                      (b)  $x - y$  plane or  $z = 0$  plane

**Working:** (a) Look at where the  $-1$  goes.

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

These do not appear in the formula booklet.

### Rotations

**E.g. 2** Find the matrix  $\mathbf{M}$  such that the point  $P(x, y, z)$  is rotated  $90^\circ$  about the  $z$ -axis.

**E.g. 3** (a) Find the matrix  $\mathbf{M}$  such that the point  $P(x, y, z)$  is rotated  $\theta^\circ$  about the  $z$ -axis.

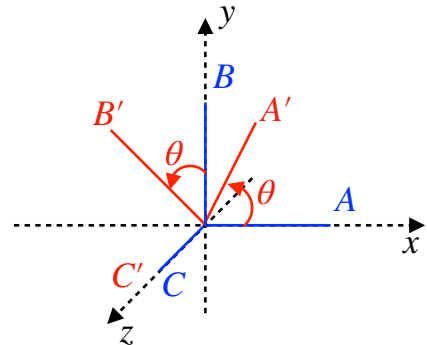
**Hint:** A positive  $\theta^\circ$  means an anti-clockwise rotation.

(b) Hence write down matrices that cause rotations of  $\theta^\circ$  about the:

(i)  $x$ -axis

(ii)  $y$ -axis

**Working:** (a)



**N.B.** These do appear in the formula booklet.

**Importance of the determinant**

The determinant gives the volume factor for the enlargement.

If the determinant is negative, the transformation changes the orientation of the object.

**E.g. 4** Find the effect on volume and orientation of the transformations defined by these matrices:

(a)  $\begin{pmatrix} 2 & -1 & 1 \\ 0 & 1 & 4 \\ 0 & -2 & 0 \end{pmatrix}$

(b)  $\begin{pmatrix} -1 & 3 & -1 \\ 0 & 1 & 2 \\ -1 & 0 & 1 \end{pmatrix}$

**Working:** (a)  $\left| \begin{pmatrix} 2 & -1 & 1 \\ 0 & 1 & 4 \\ 0 & -2 & 0 \end{pmatrix} \right| = \left| \begin{pmatrix} 2 & -1 & 1 \\ 0 & 1 & 4 \\ 0 & -2 & 0 \end{pmatrix}^T \right| = \left| \begin{pmatrix} 2 & 0 & 0 \\ -1 & 1 & -2 \\ 1 & 4 & 0 \end{pmatrix} \right|$   
 $= 16$

The transformation enlarges the volume by a factor of 16 but does not change an objects' orientation.

**Enlargements and stretches**

**E.g. 5** Find the matrix in 3-D which causes:

(a) an enlargement by a factor 2,

(b) a stretch by a factor of 3 in the  $x$ - and  $z$ -directions.

**Working:** (a)  $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \rightarrow \begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix}$        $\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \rightarrow \begin{pmatrix} 0 \\ 2 \\ 0 \end{pmatrix}$        $\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \rightarrow \begin{pmatrix} 0 \\ 0 \\ 2 \end{pmatrix}$

So the matrix is  $\begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{pmatrix}$

**Compound transformations**

**E.g. 6** Find the matrix which causes an enlargement scale factor 4 followed by a reflection in the  $y - z$  plane.

**Exercise**

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**Summary**

Reflection (in the given plane)		
$x = 0$ or $y - z$ plane	$y = 0$ or $x - z$ plane	$z = 0$ or $x - y$ plane
$\begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$

Rotations (about the given axis)		
$x$ -axis	$y$ -axis	$z$ -axis
$\begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos \theta & -\sin \theta \\ 0 & \sin \theta & \cos \theta \end{pmatrix}$	$\begin{pmatrix} \cos \theta & 0 & \sin \theta \\ 0 & 1 & 0 \\ -\sin \theta & 0 & \cos \theta \end{pmatrix}$	$\begin{pmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix}$